SPECIFICATION AMENDMENTS:

Please amend the last paragraph of page 5 as follows--

The elevating platform system 1 has a parallelogram-shaped lifting mechanism whose basic elements include two carrier arms 3, 4 which are borne for rotation about a common rotational axis 5 at the rotational points A_1 and A_2 at the side facing the vehicle. A lifting cylinder lever 6 and a lifting cylinder 7 are disposed below the first carrier arm 3. The lifting cylinder 7 is borne proximate the vehicle for pivoting about the pivot point C_1 and the lifting cylinder ~~lever 7~~lever 6 is borne for rotation at point A_1 independent of the first supporting arm 3 and also about the rotational axis 5. The lifting cylinder 7 engages the lifting cylinder lever 6 at location C_2 to form a first triangle C_1, C_2, A_1. The force of the lifting cylinder 7 is introduced into the lifting cylinder lever 6 at point C_2 which describes radial motion about its point of rotation A_1. --.

Please amend the first paragraph of page 8 as follows--

The connecting plate 13 is bent at two locations and defines a large window 15 through which the first support arm 3', the two support arms 6a and 6b of the lifting cylinder lever 6 and the lifting cylinder lever 7 extend. An upper support 16 of the connecting plate 13 seats on both arms 6a and 6b. The connecting plate 13 is attached at 100 mm separation with respect to rotational point C_3 of the lifting cylinder lever 6 by means of a through bolt 17 which extends through both arms 6a, 6b of the lifting cylinder lever and has a hollow separating bolt 18 which separates the two arms 6a, 6b. The first carrier arm 3' is borne on the separation bolt 18 and its end seats on the rubber spring 11. The second attachment of the connecting plate 13 is effected by second screw 19 which only connects the inner sided arm 6a of the lifting cylinder lever to

the connecting plate 13. This screw connection is only used to prevent the connecting device 12 from rotating in an upward direction in the event of extreme lower travel protective forces such that the lower region of the ~~window 14~~window 15 does not strike against the lifting cylinder piston arm. The operational forces which are introduced from the lifting cylinder 7 or its triangle of forces via the arm 6a, 6b of the lifting cylinder lever 6 and into the connecting device 12 are transferred solely by means of the positive connection with which the two arms 6a, 6b transfer load to the upper support 16 of the connecting device 12. Without the seating of the connecting plate 13 on the outer arms 6b, the entire lifting arm e.g. lifting arm 3', arms 6a and 6b of the lifting cylinder 7 could twist under load due to the one sided attachment of the connecting plate 13 to the inner sided arm 6a. --.